

Figure 2

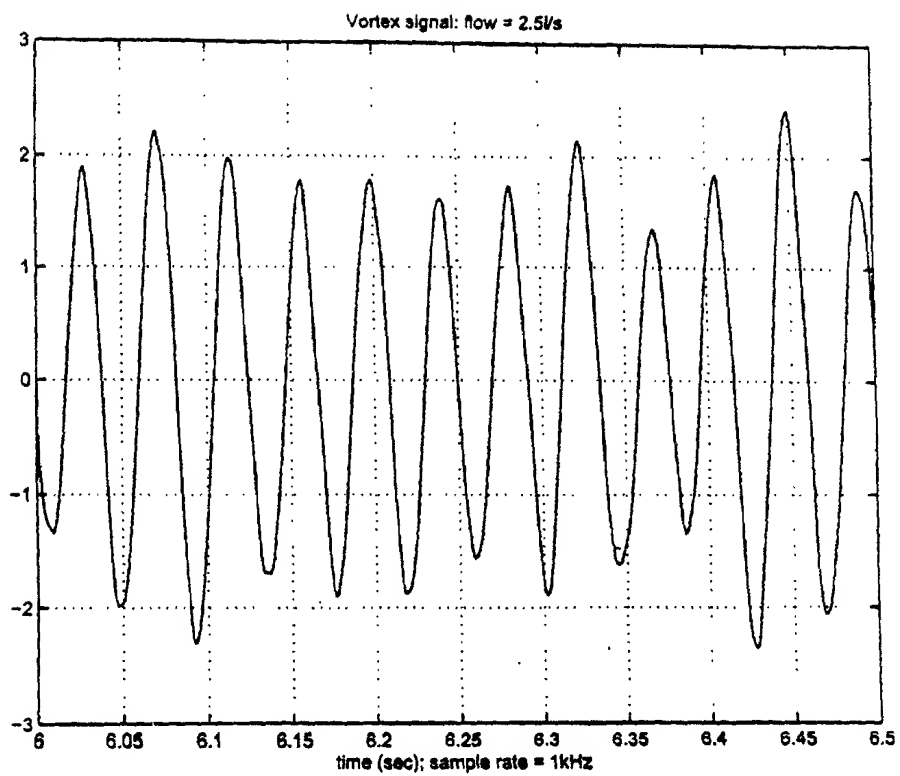


Figure 3a

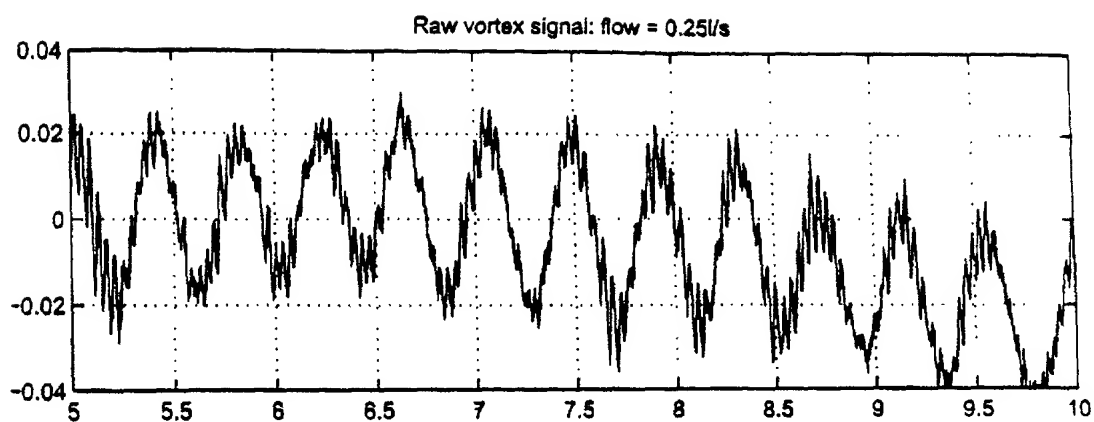


Figure 3b

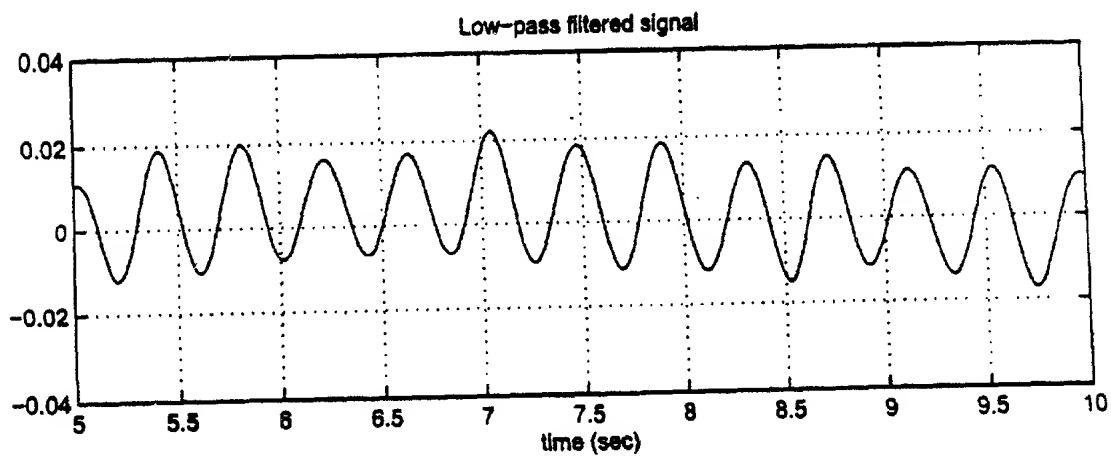


Figure 3c

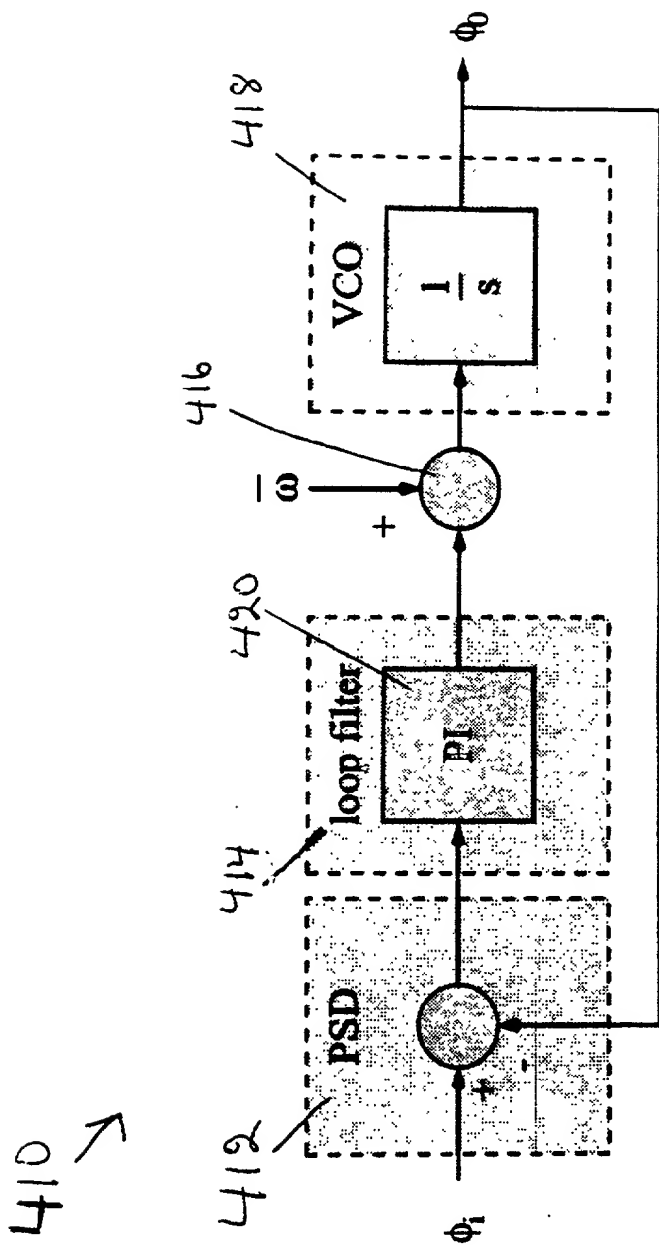


Figure 4

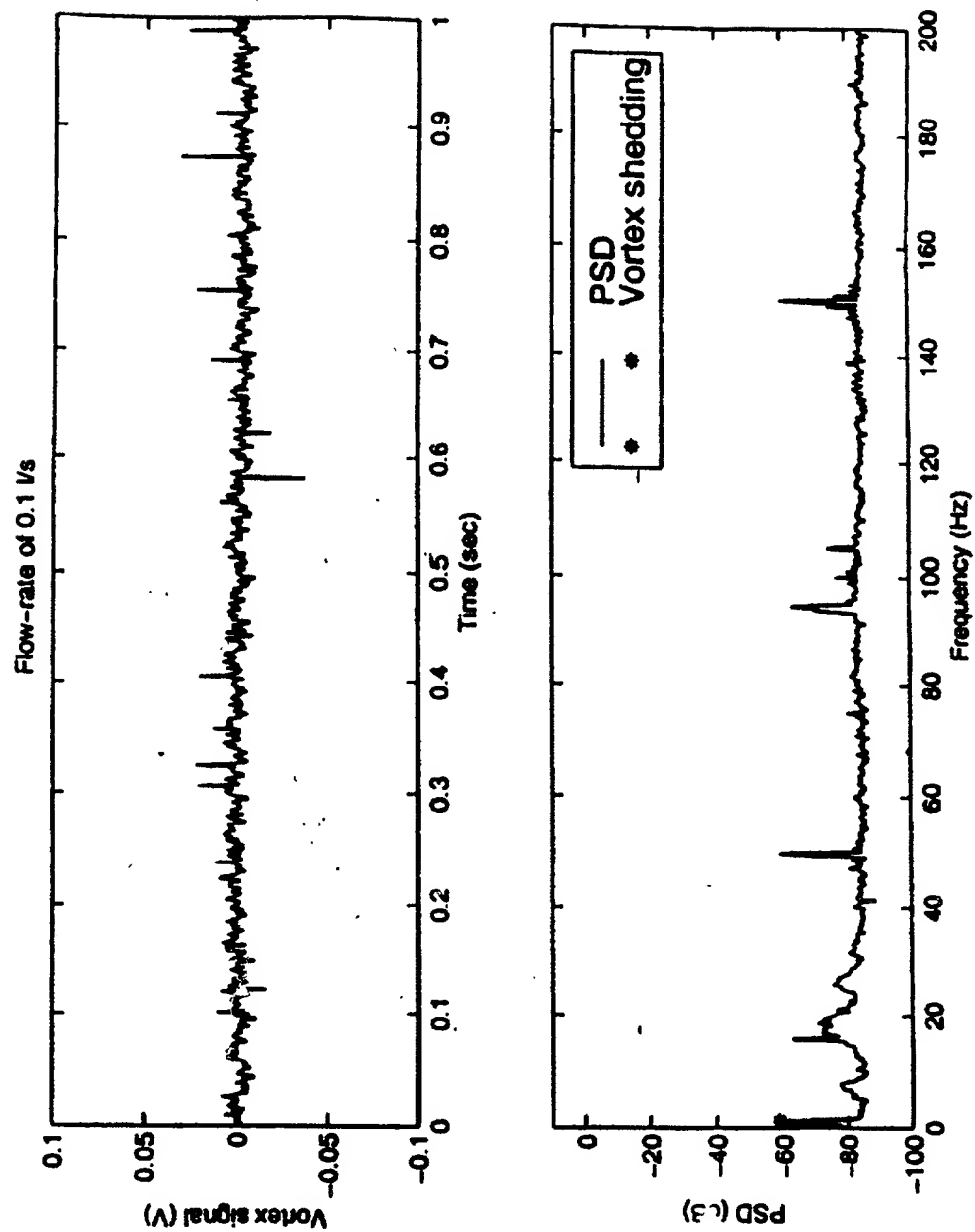
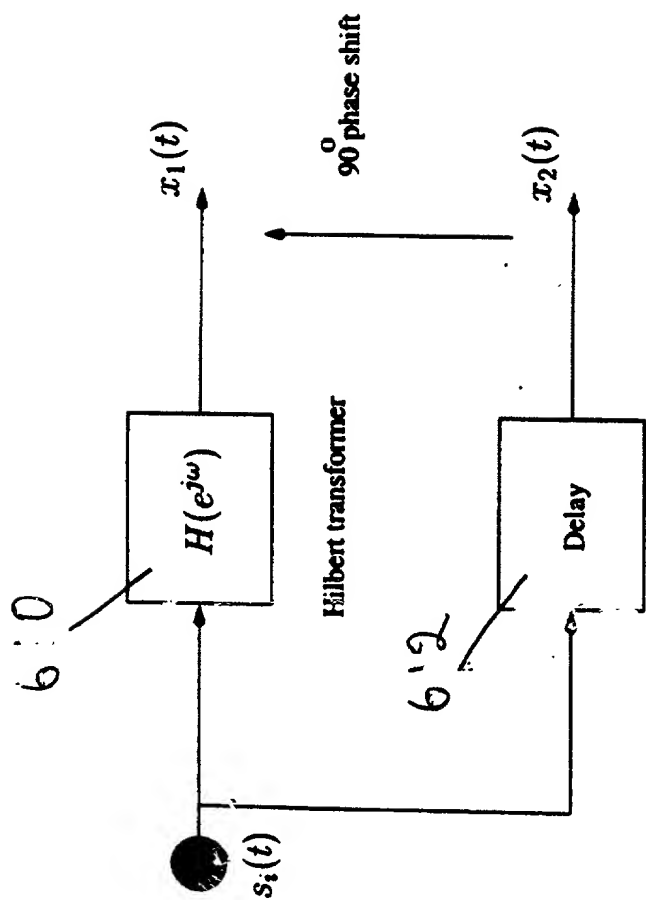


Figure 5



$$\angle x_1(t) - \angle x_2(t)$$

Figure 6

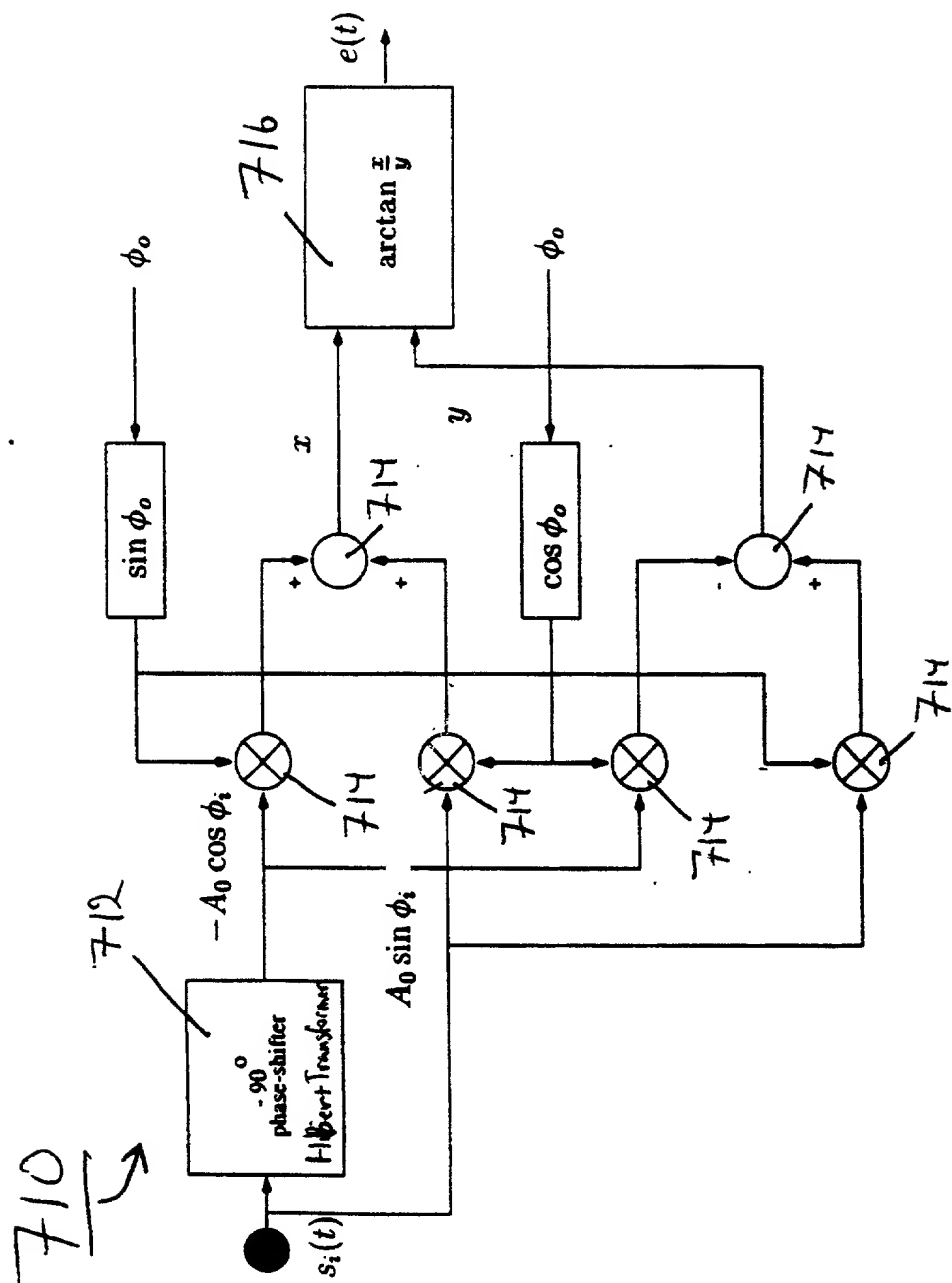


Figure 7



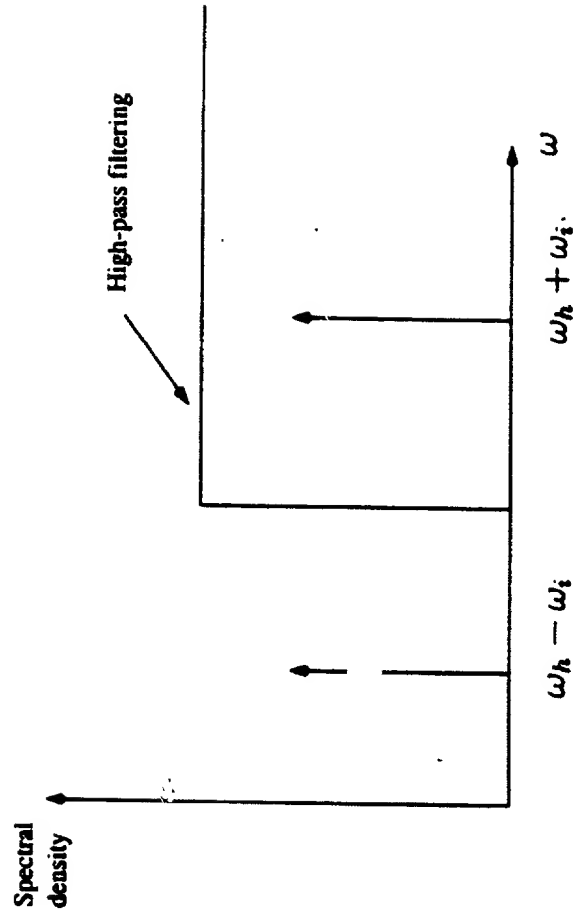


Figure 8

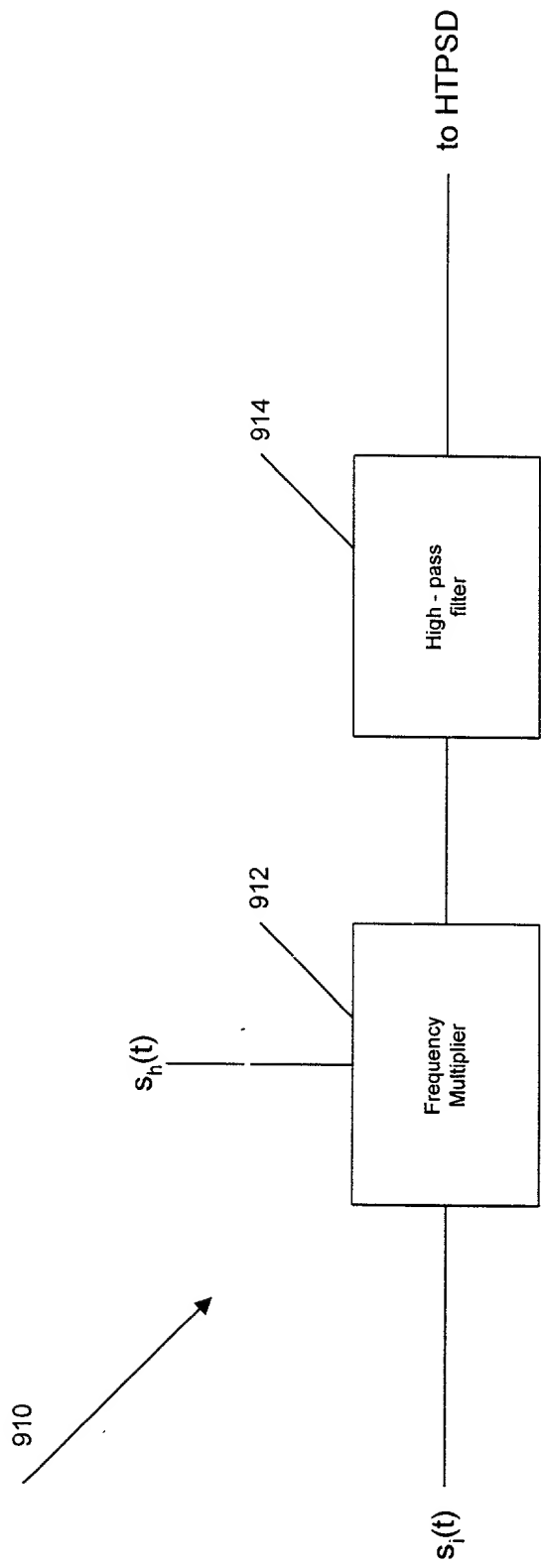


Figure 9

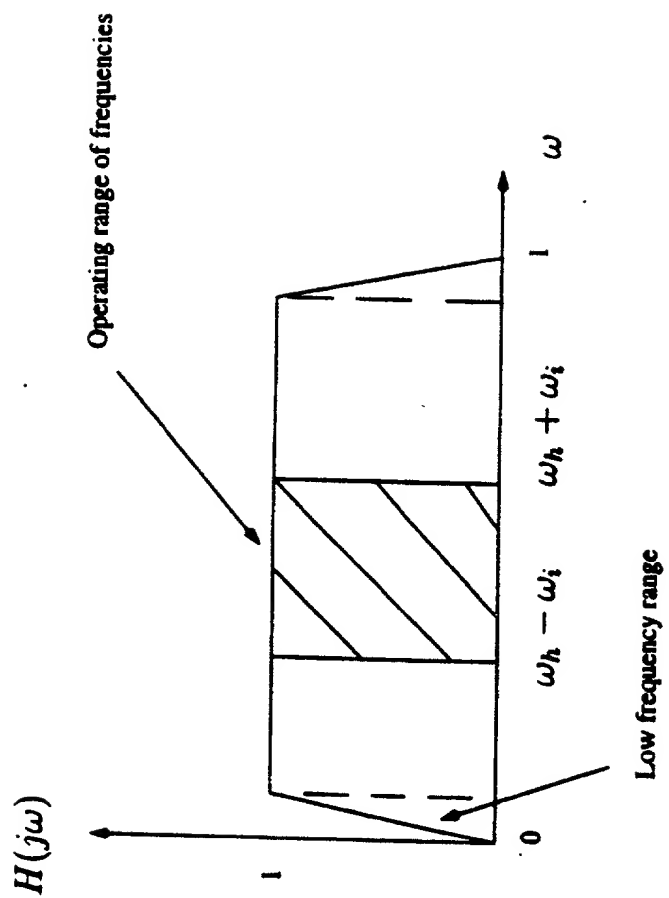


Figure 10

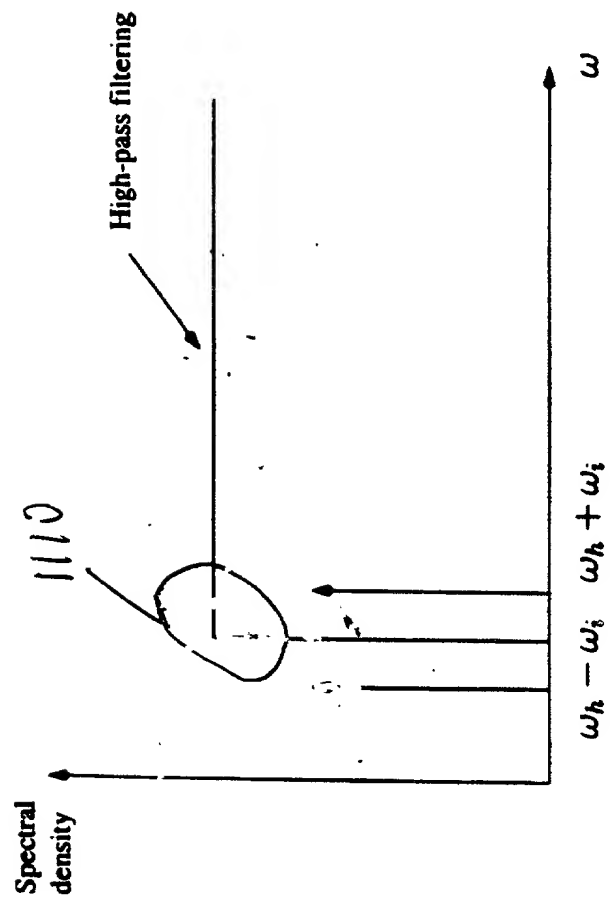


Figure 11

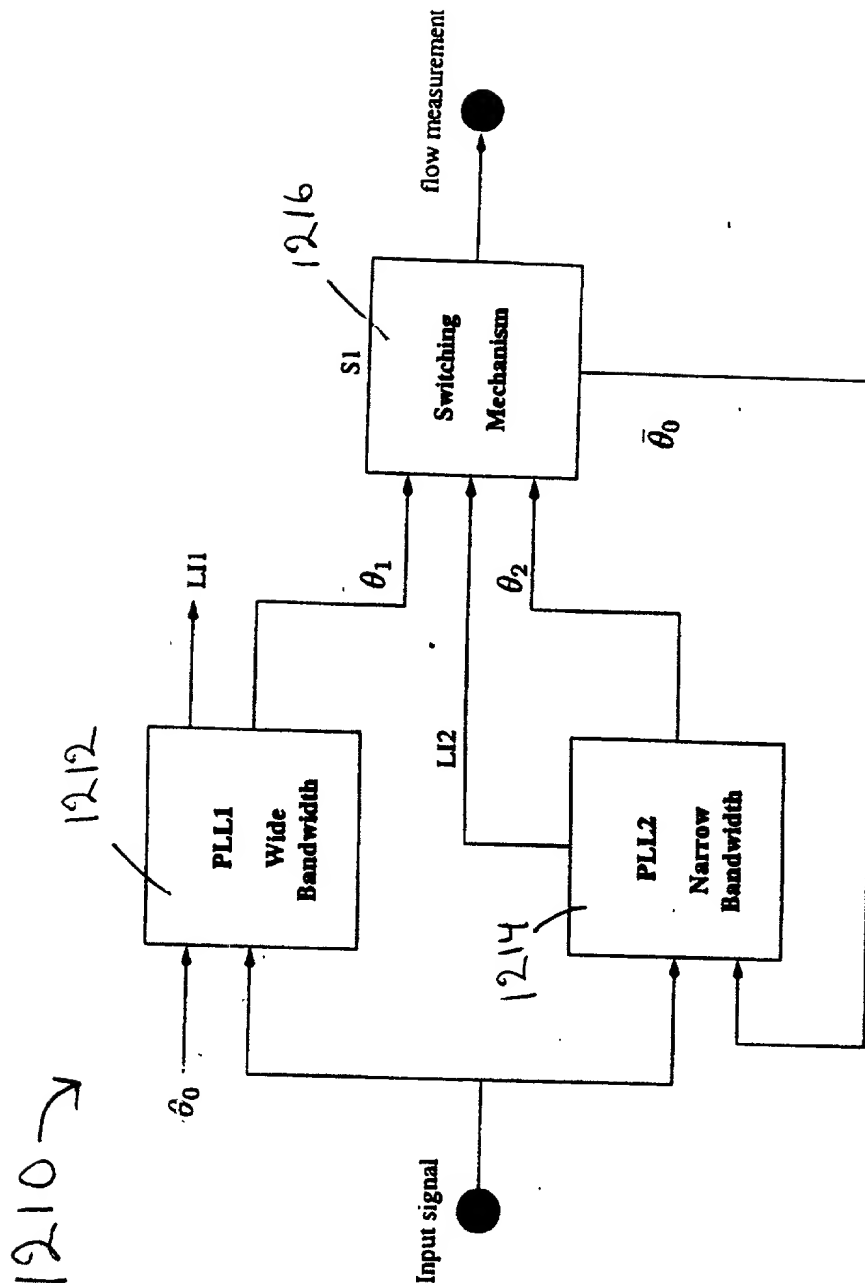


Figure 12

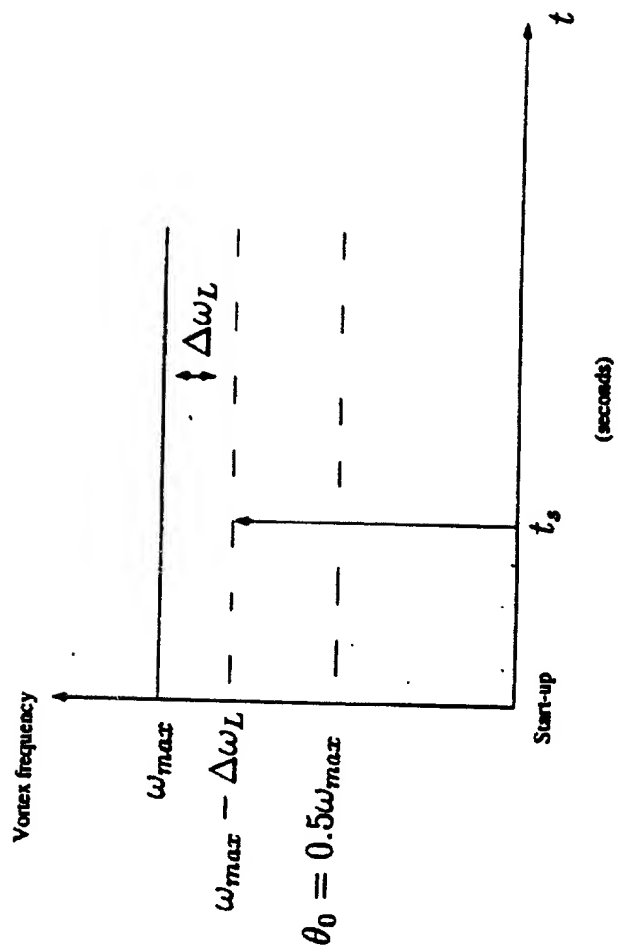


Figure 13

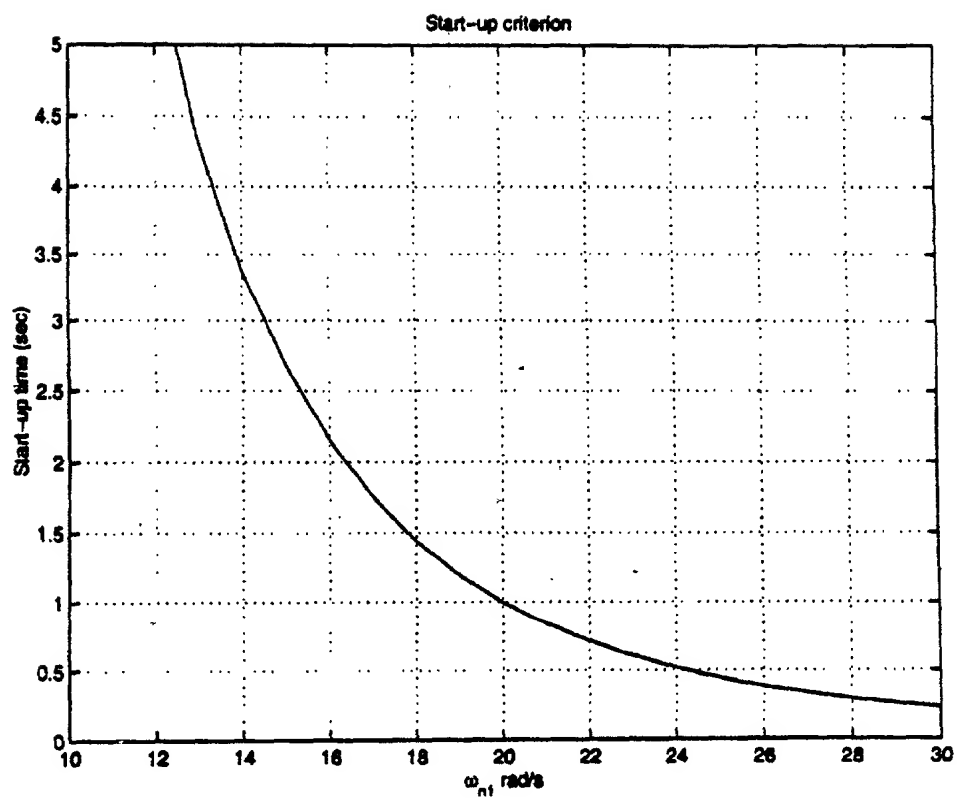


Figure 14.

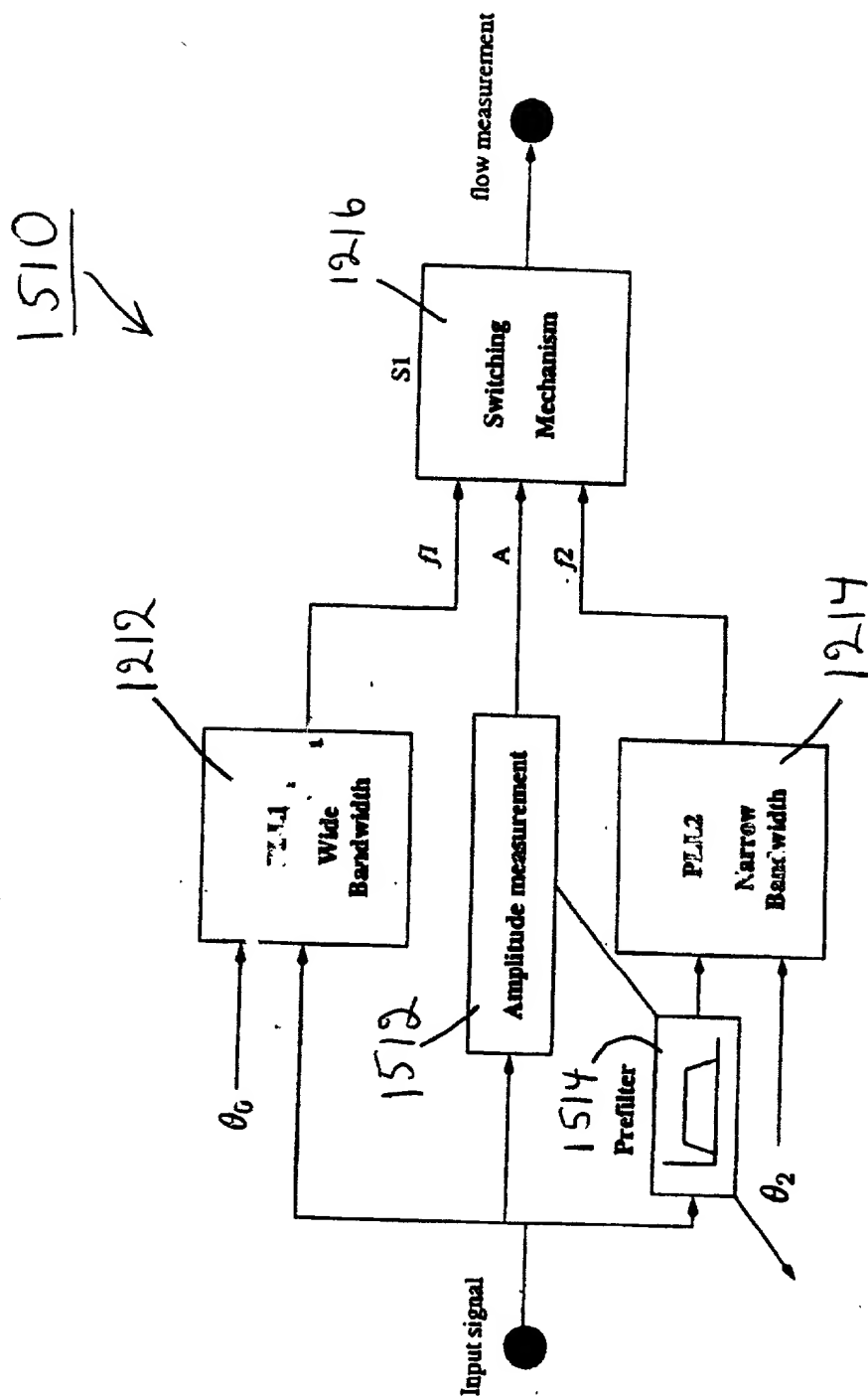


Figure 15



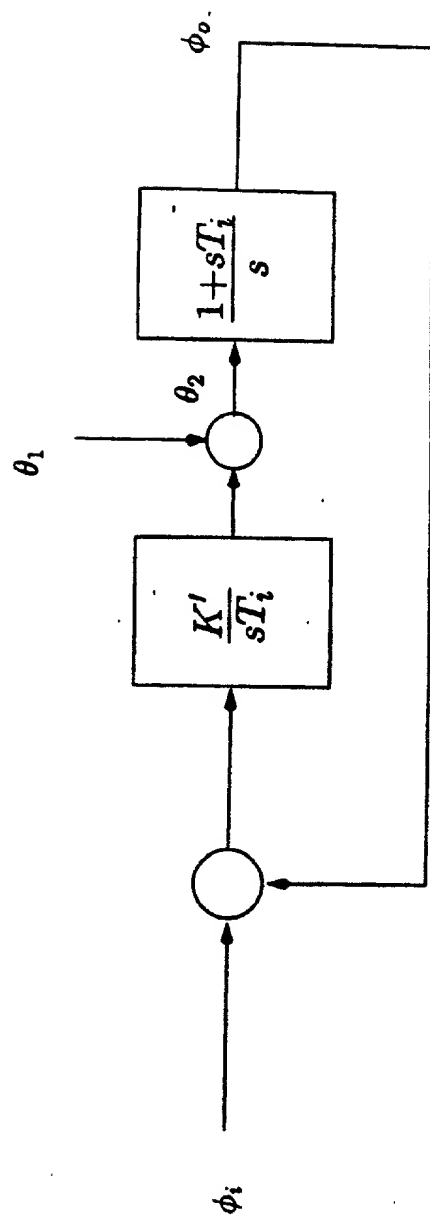


Figure 16

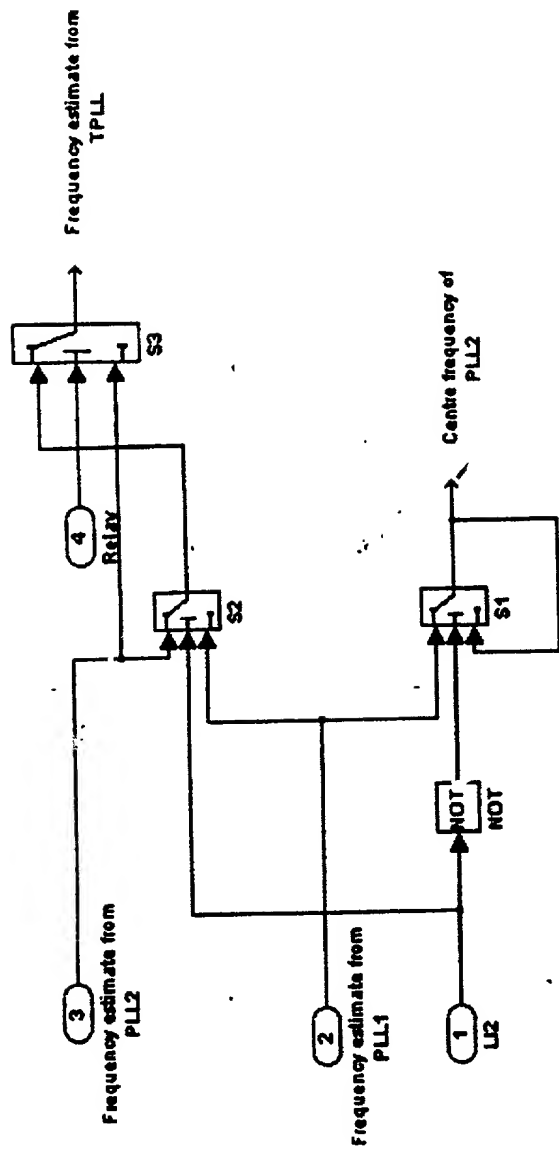


Figure 17

1800  
↓

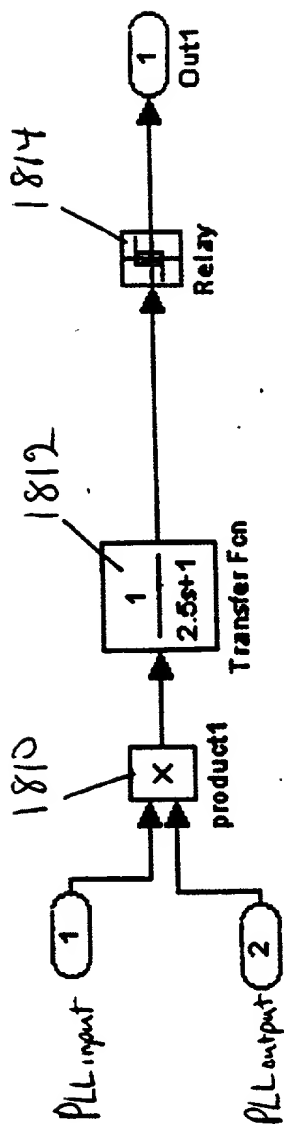


Figure 18

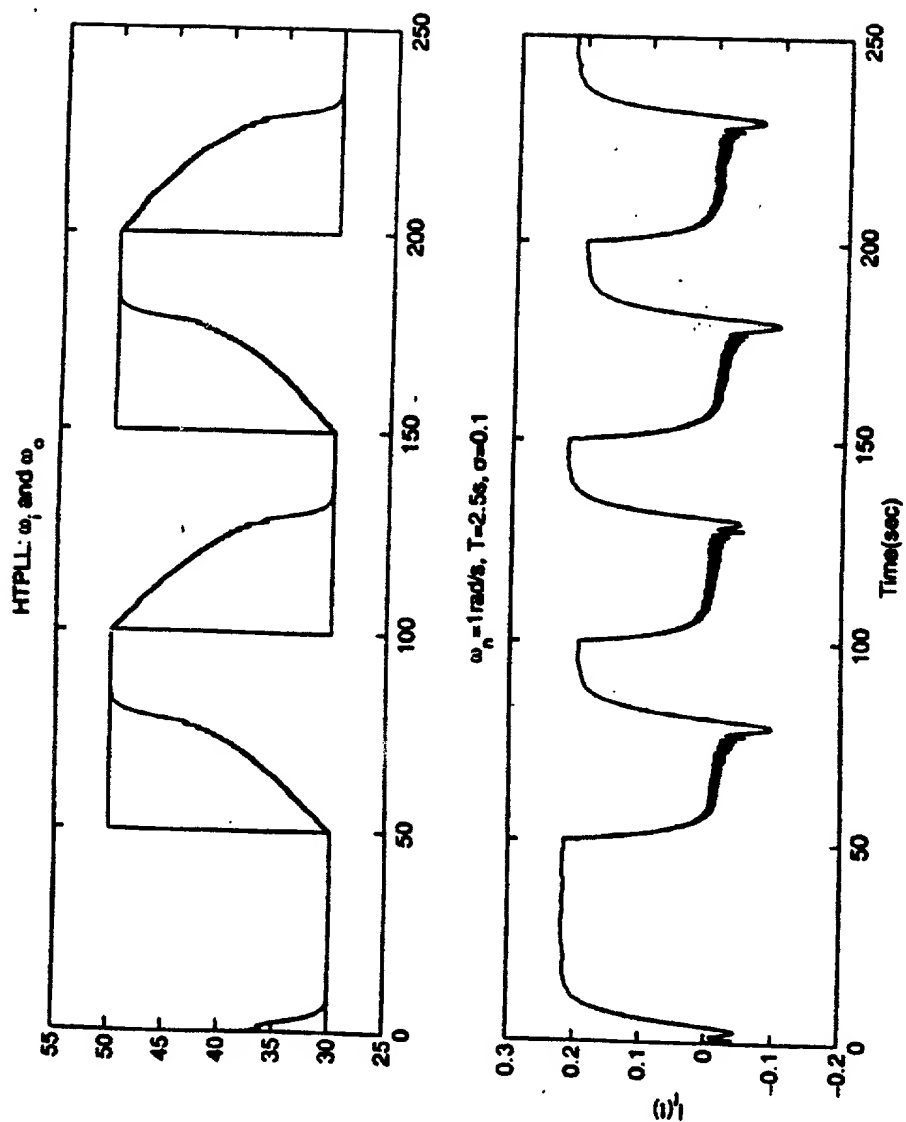


Figure 19

...

2000

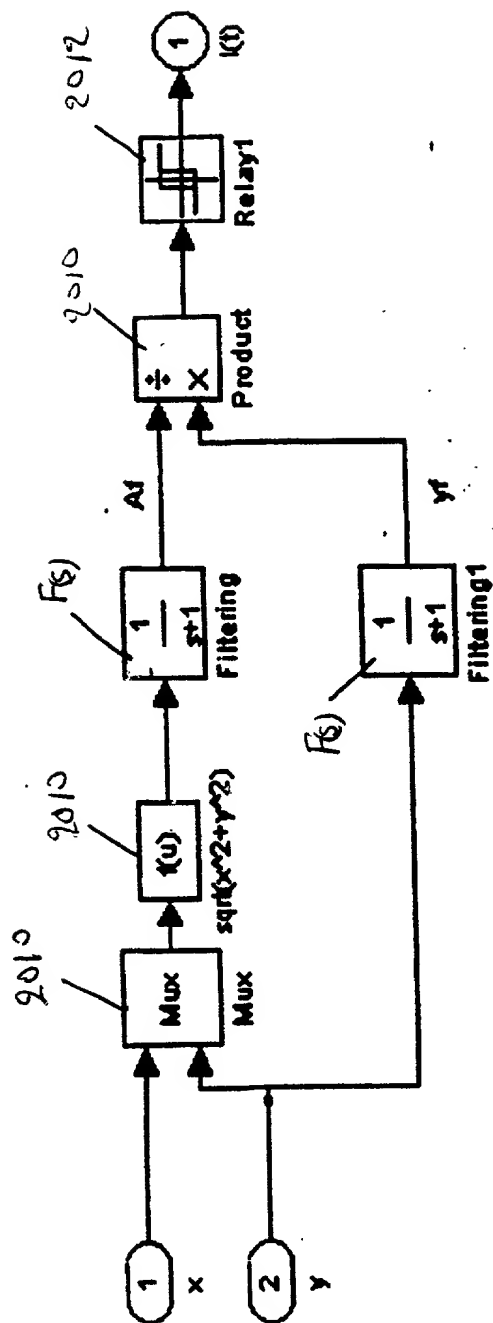


Figure 20

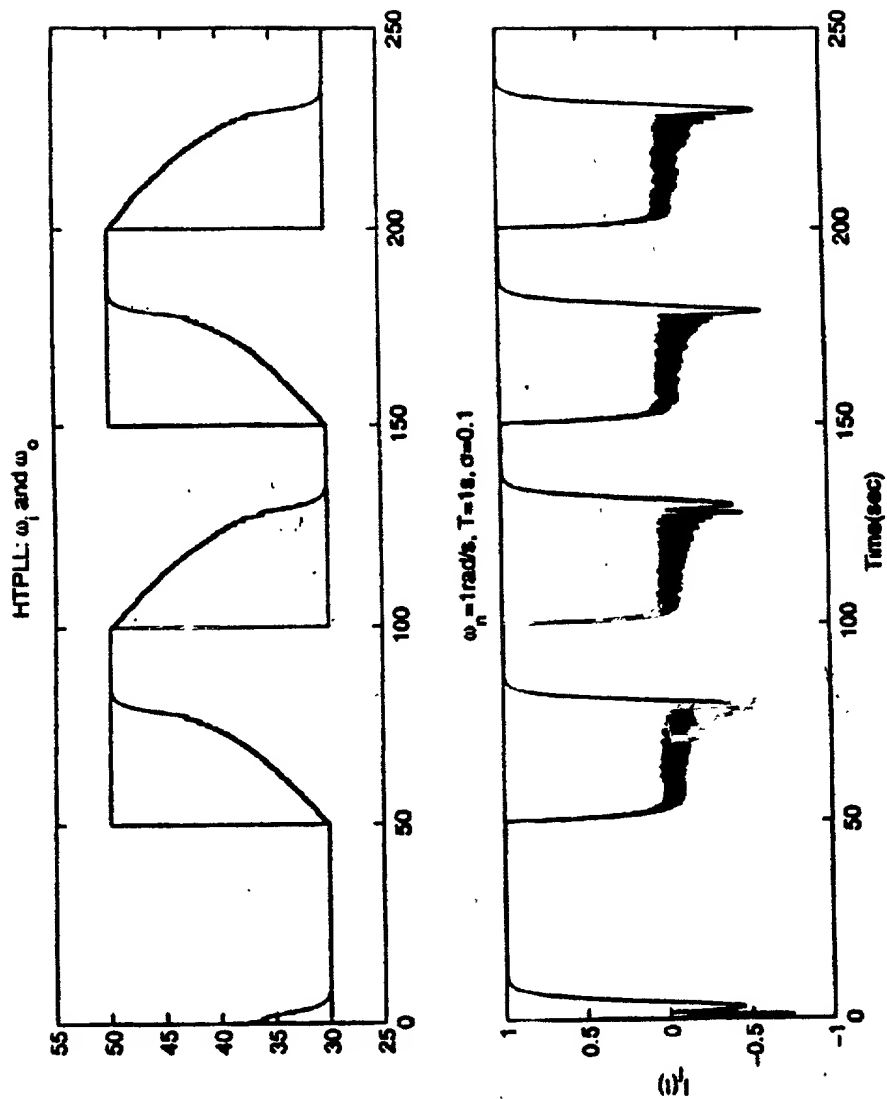


Figure 21

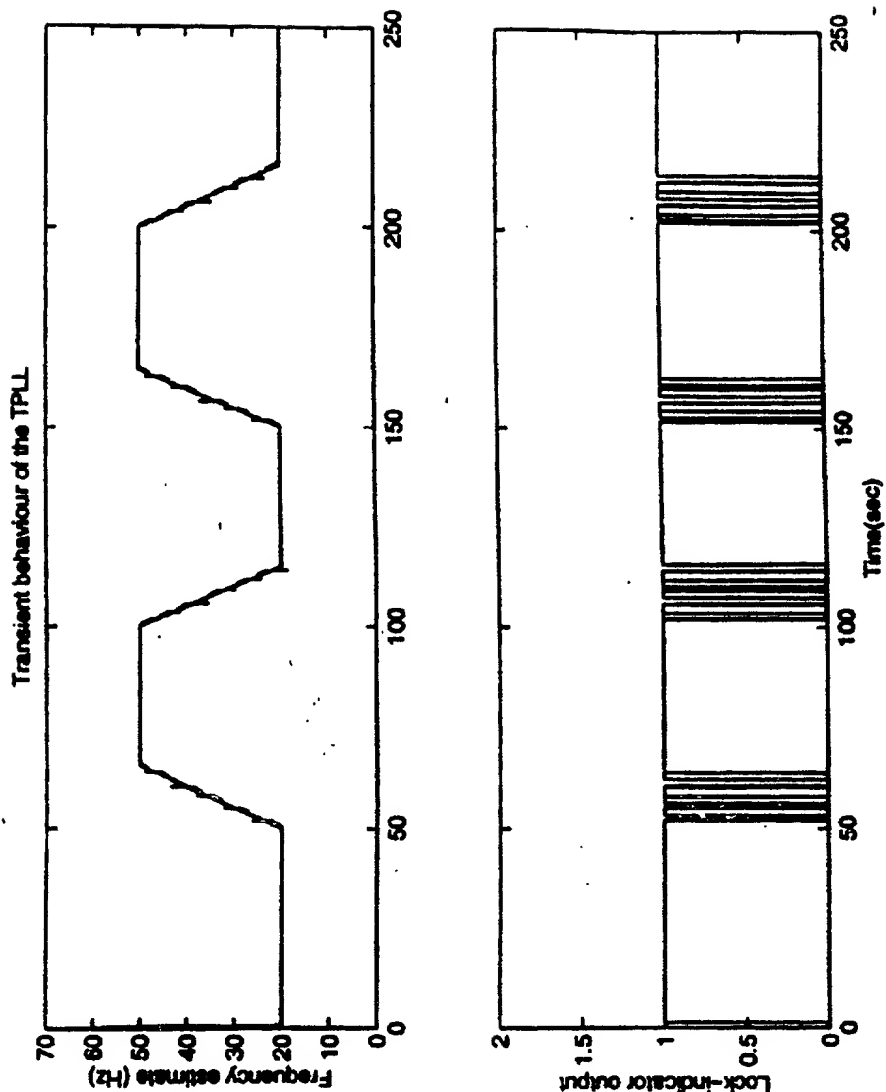


Figure 22

2300

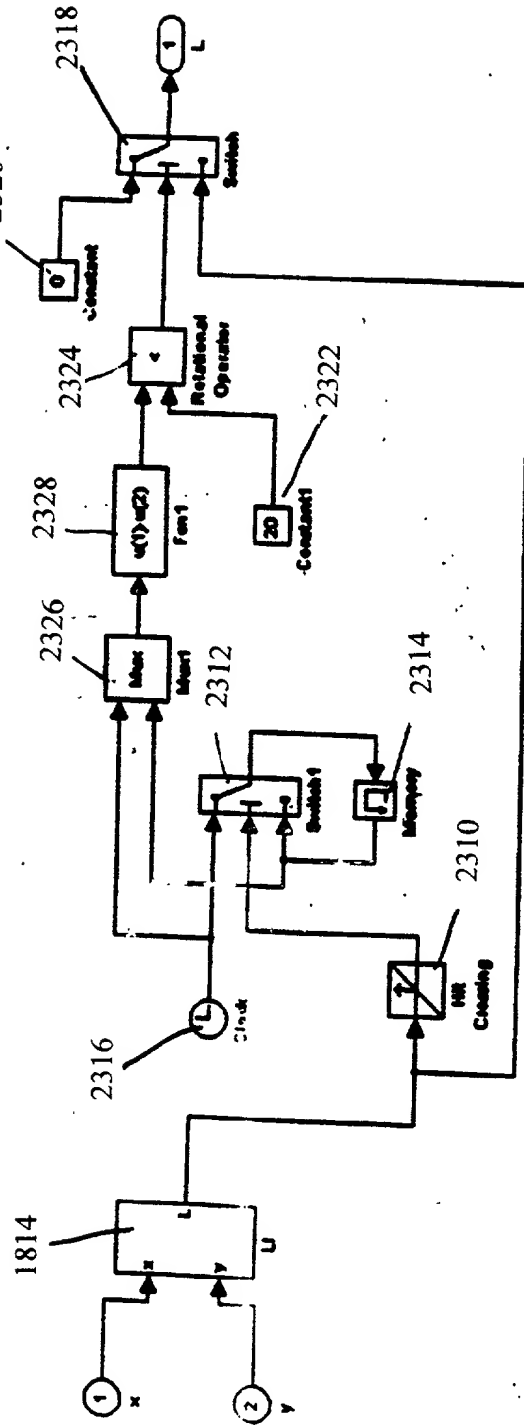


Figure 23



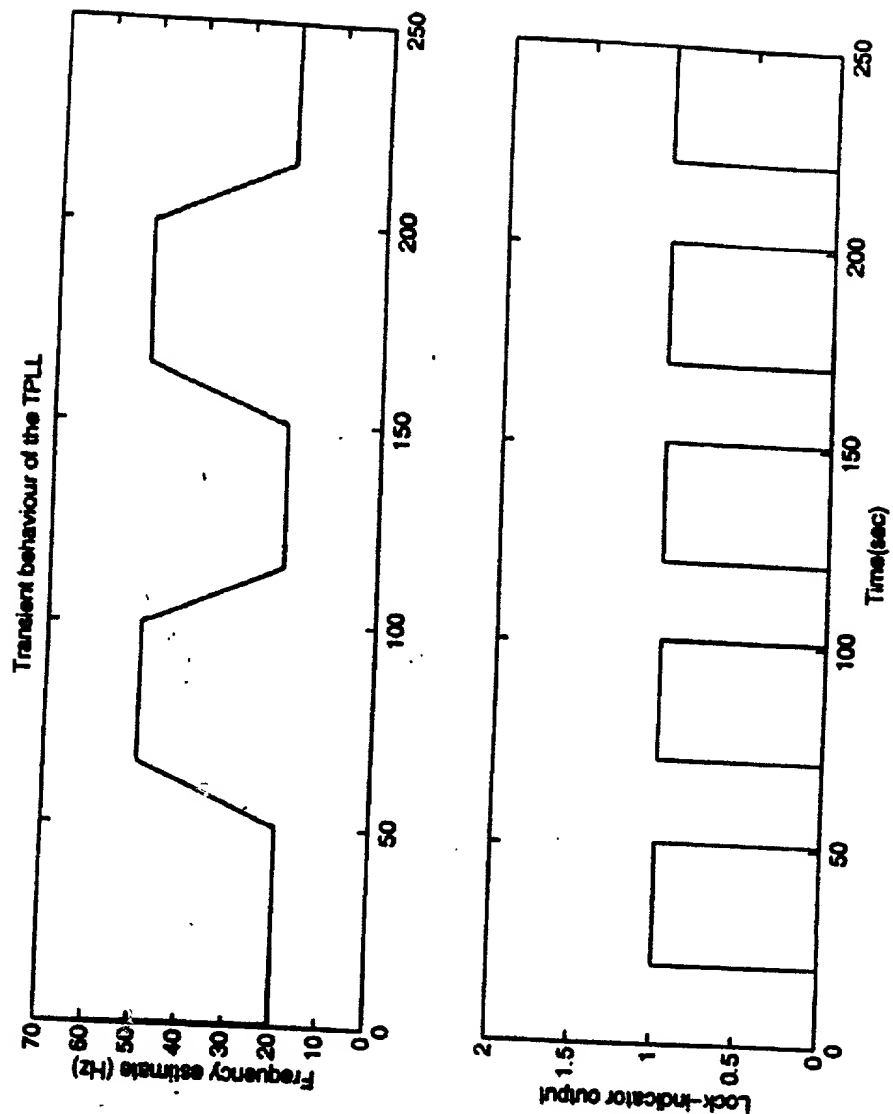
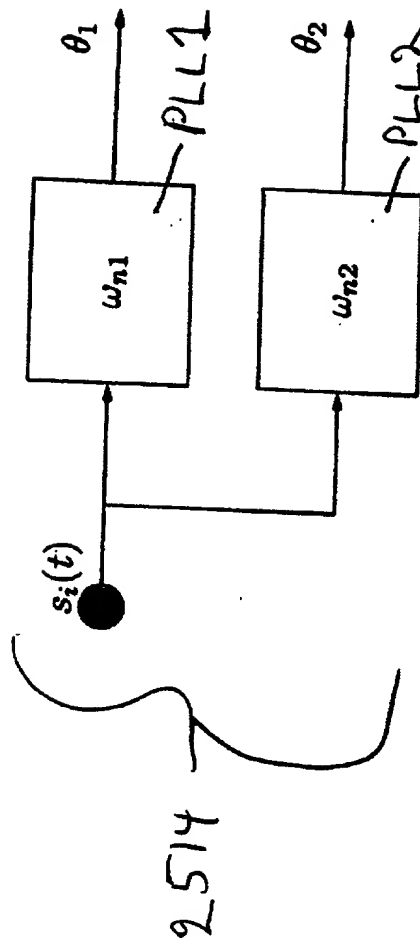
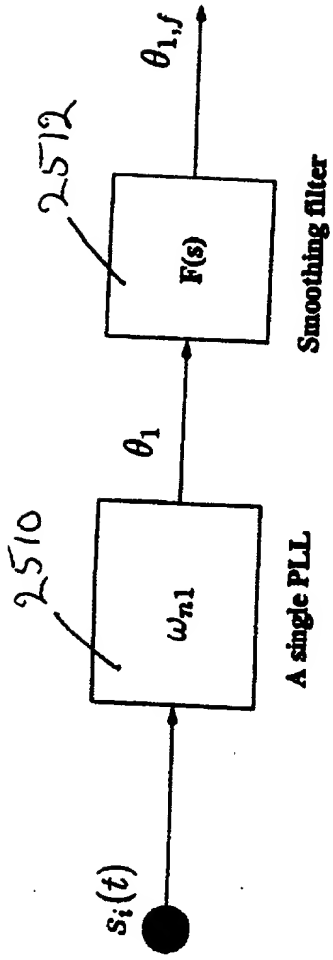


Figure 24



DUAL PLL PROCESSOR

Figure 25

66000-6260

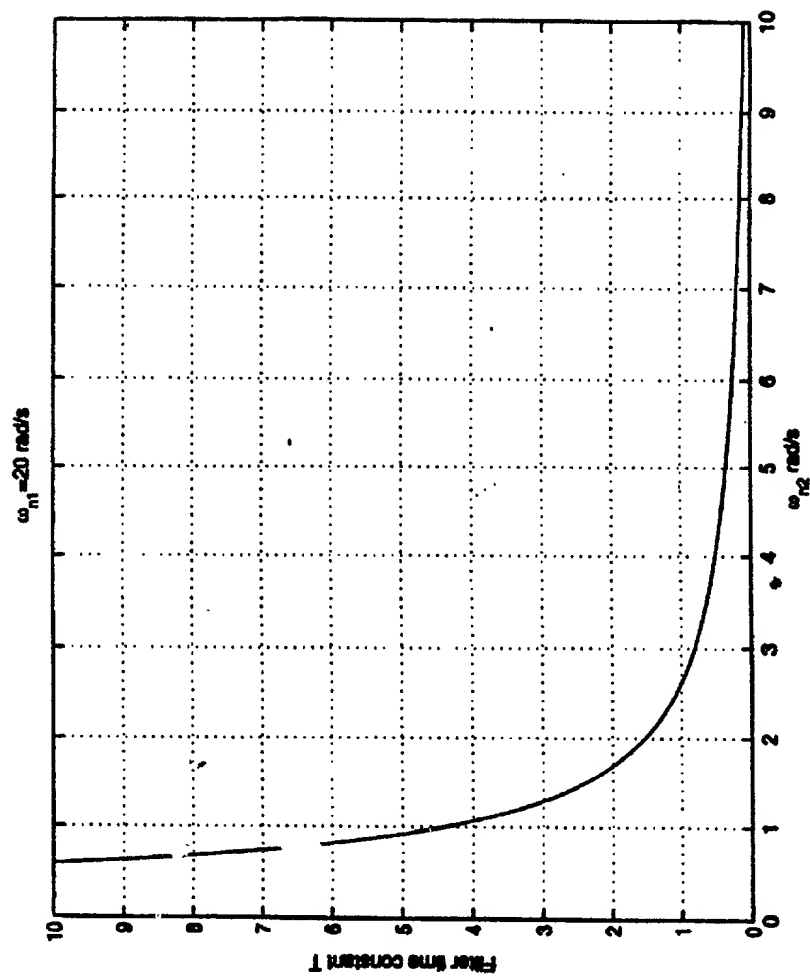


Figure 26

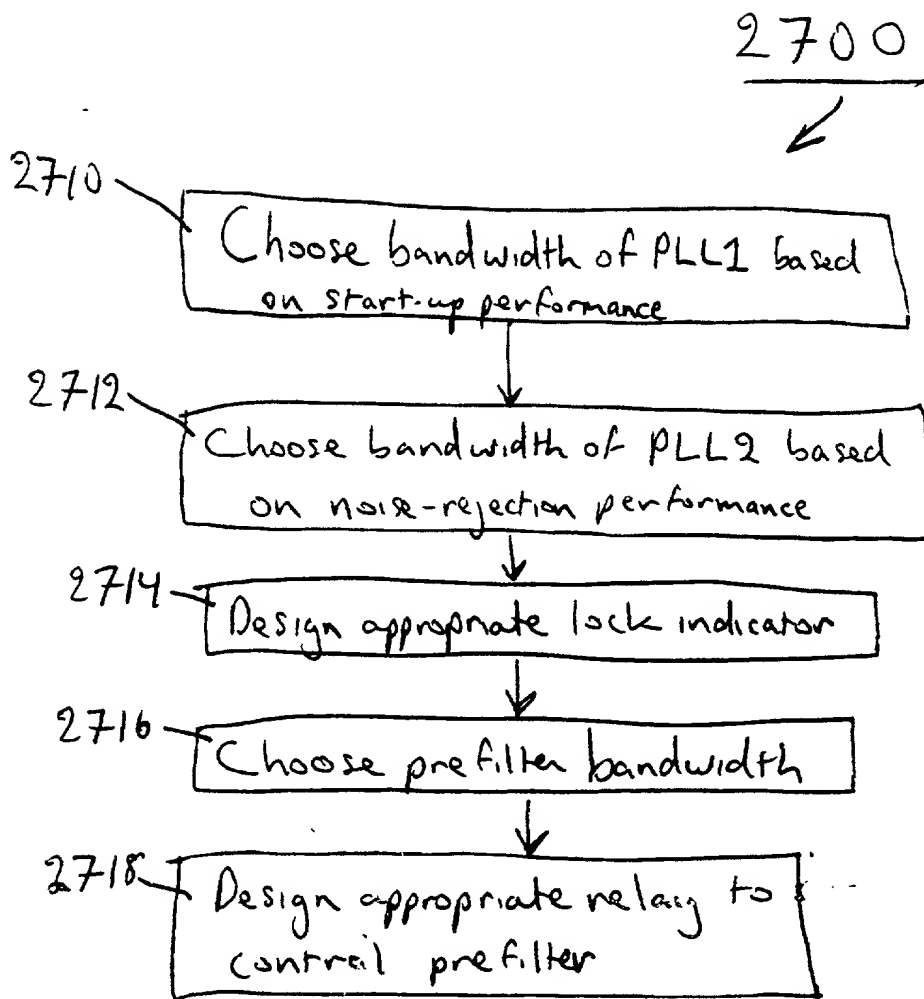


Figure 27

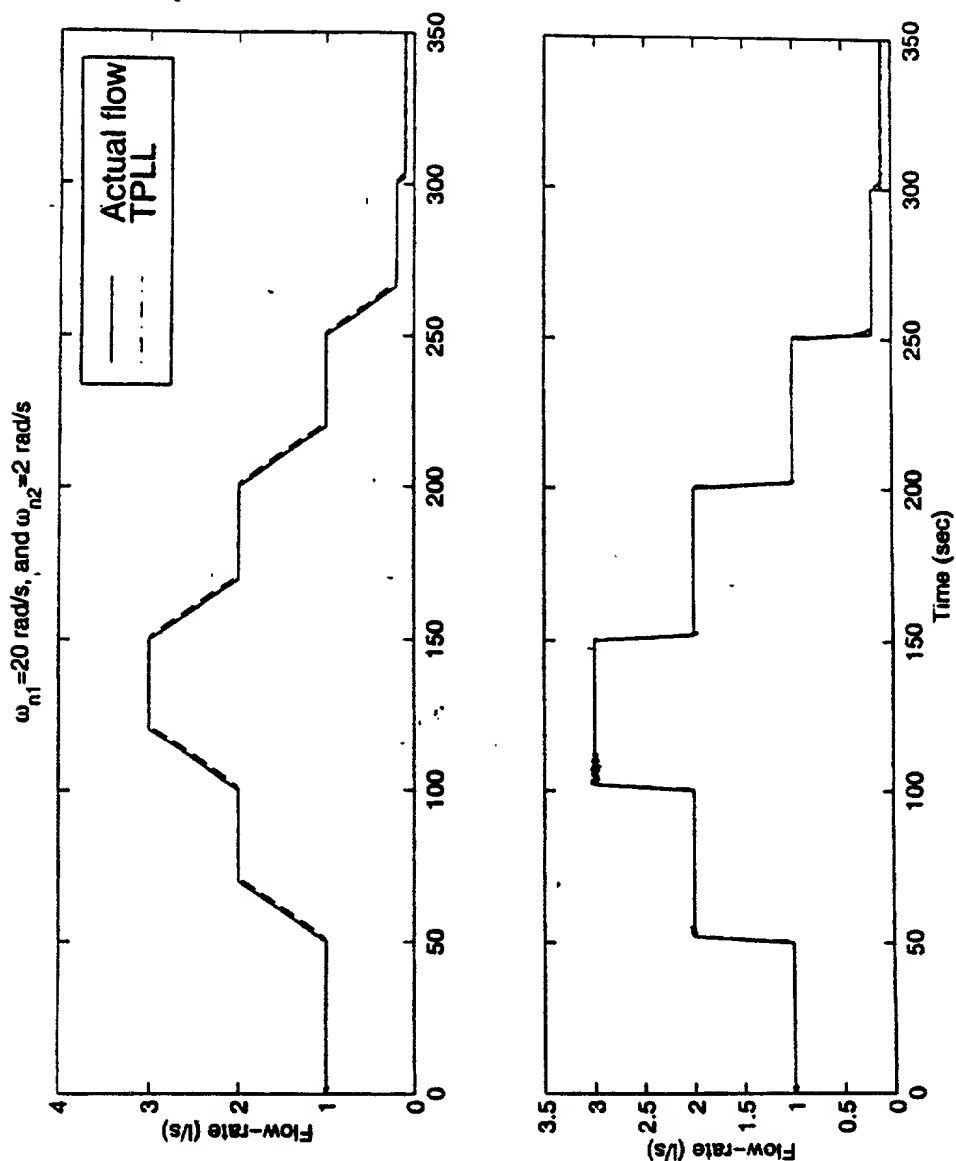


Figure 28

Patent 6,666,666

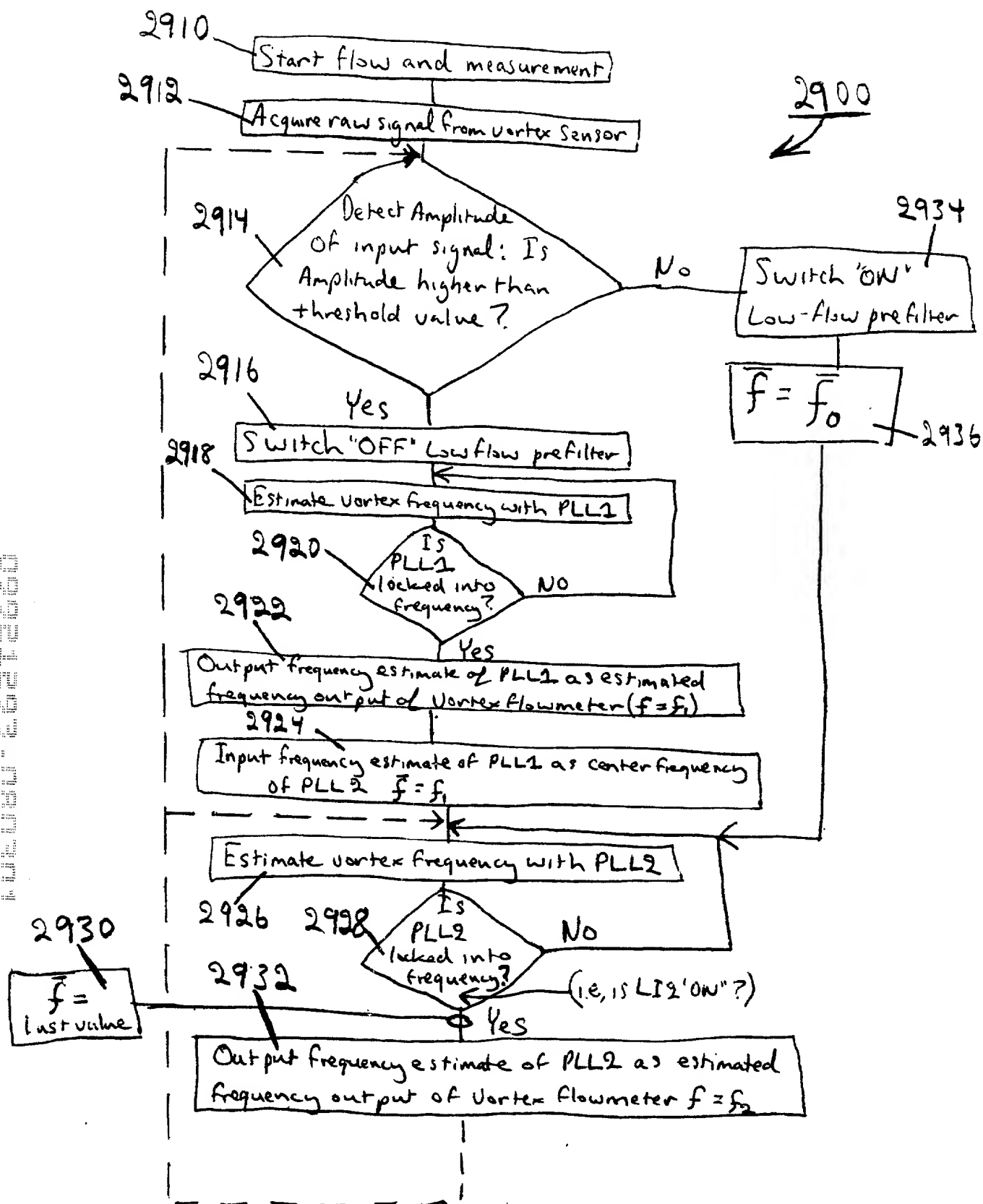


Figure 29

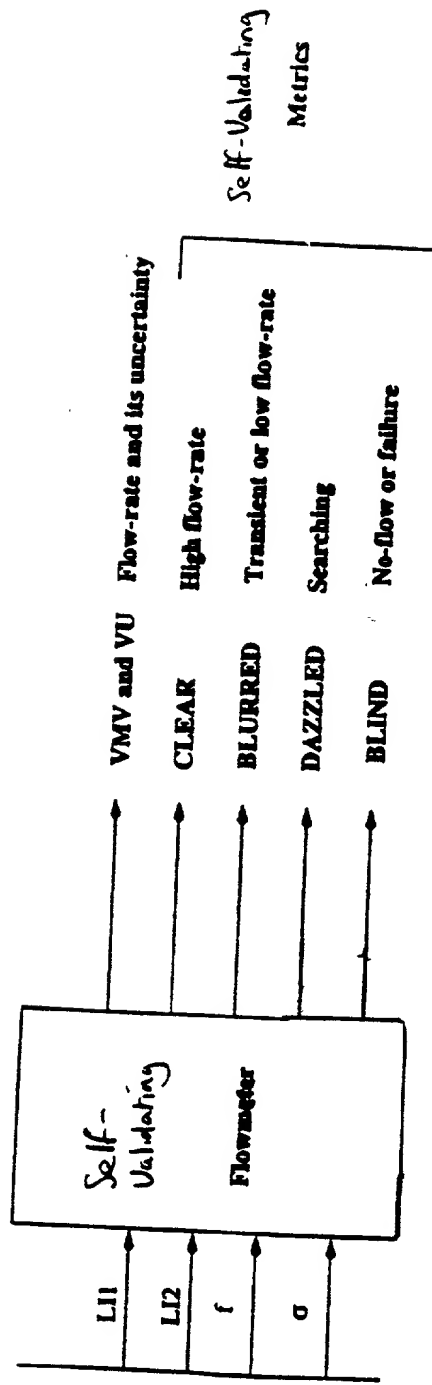


Figure 30